Thread-Level Parallelism

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Today

Parallel Computing Hardware

- Multicore
 - Multiple separate processors on single chip
- Hyperthreading
 - Efficient execution of multiple threads on single core

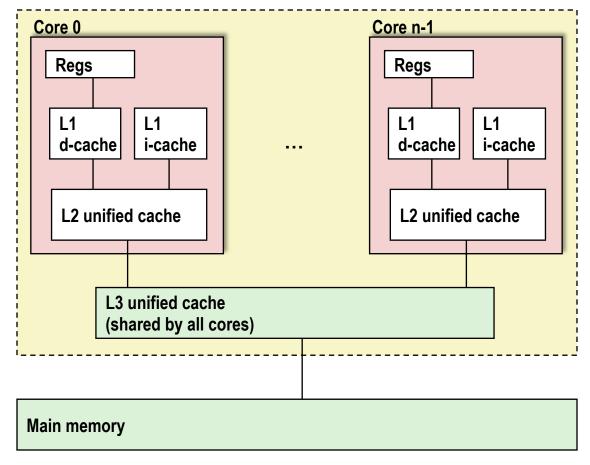
Thread-Level Parallelism

- Splitting program into independent tasks
 - Example 1: Parallel summation
- Divide-and conquer parallelism
 - Example 2: Parallel quicksort

Exploiting parallel execution

- So far, we've used threads to deal with I/O delays
 - e.g., one thread per client to prevent one from delaying another
- Multi-core CPUs offer another opportunity
 - Spread work over threads executing in parallel on N cores
 - Happens automatically, if many independent tasks
 - e.g., running many applications or serving many clients
 - Can also write code to make one big task go faster
 - by organizing it as multiple parallel sub-tasks
- Our core i7 (Haswell) machines can execute 4 threads at once
 - 4 cores, with hyperthreading turned off.
 - Theoretical speedup of 4x, never achieved in our benchmarks

Multicore Processor



■ Intel Core i7 Haswell Processor

Multiple processors operating with coherent view of memory

Example 1: Parallel Summation

- Sum numbers 0, ..., n-1
 - Should add up to ((n-1)*n)/2
- Partition values 1, ..., n-1 into t ranges
 - [n/t] values in each range
 - Each of t threads processes 1 range
 - For simplicity, assume n is a multiple of t
- Let's consider different ways that multiple threads might work on their assigned ranges in parallel

First attempt: psum-mutex

Simplest approach: Threads sum into a global variable protected by a semaphore mutex.

```
void *sum mutex(void *vargp); /* Thread routine */
/* Global shared variables */
long gsum = 0; /* Global sum */
long nelems_per_thread; /* Number of elements to sum */
sem t mutex;
                    /* Mutex to protect global sum */
int main(int argc, char **argv)
{
   long i, nelems, log_nelems, nthreads, myid[MAXTHREADS];
    pthread t tid[MAXTHREADS];
    /* Get input arguments */
    nthreads = atoi(argv[1]);
   log_nelems = atoi(argv[2]);
    nelems = (1L << log nelems);</pre>
    nelems_per_thread = nelems / nthreads;
    sem init(&mutex, 0, 1);
```

psum-mutex (cont)

Simplest approach: Threads sum into a global variable protected by a semaphore mutex.

```
/* Create peer threads and wait for them to finish */
for (i = 0; i < nthreads; i++) {</pre>
    myid[i] = i;
    Pthread create(&tid[i], NULL, sum mutex, &myid[i]);
for (i = 0; i < nthreads; i++)</pre>
   Pthread_join(tid[i], NULL);
/* Check final answer */
if (gsum != (nelems * (nelems-1))/2)
    printf("Error: result=%ld\n", gsum);
exit(0);
```

psum-mutex Thread Routine

Simplest approach: Threads sum into a global variable protected by a semaphore mutex.

```
/* Thread routine for psum-mutex.c */
void *sum_mutex(void *vargp)
    long myid = *((long *)vargp);  /* Extract thread ID */
    long start = myid * nelems per thread; /* Start element index */
    long end = start + nelems per thread; /* End element index */
    long i;
    for (i = start; i < end; i++) {</pre>
       P(&mutex);
        gsum += i;
       V(&mutex);
    return NULL;
```

psum-mutex Performance

Core i7 (Haswell) system with 4 cores, n=2³¹

Threads (Cores)	1 (1)	2 (2)	4 (4)	8 (4)	16 (4)
psum-mutex (secs)	68	432	719	552	599

Nasty surprise:

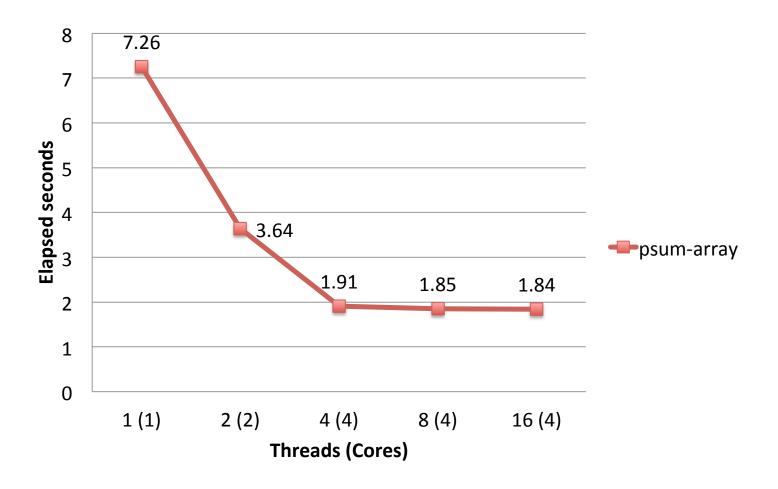
- Single thread is very slow
- Gets slower as we use more cores

Next Attempt: psum-array

- Peer thread i sums into global array element psum[i]
- Main waits for theads to finish, then sums elements of psum
- Eliminates need for mutex synchronization

psum-array Performance

Orders of magnitude faster than psum-mutex



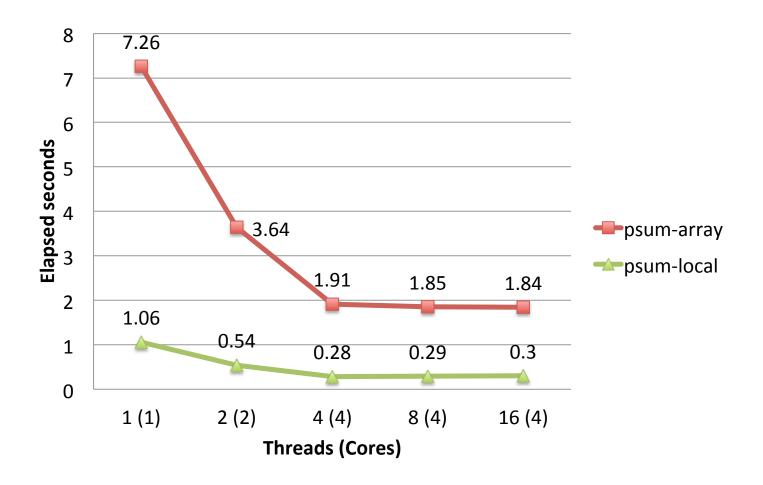
Next Attempt: psum-local

 Reduce memory references by having peer thread i sum into a local variable (register)

```
/* Thread routine for psum-local.c */
void *sum local(void *varqp)
    long myid = *((long *)vargp);
                                 /* Extract thread ID */
    long start = myid * nelems_per_thread; /* Start element index */
    long end = start + nelems per thread; /* End element index */
    long i, sum = 0;
    for (i = start; i < end; i++) {</pre>
        sum += i;
    psum[myid] = sum;
    return NULL:
                                                            psum-local.c
```

psum-local Performance

Almost an order of magnitude faster than psum-array



Characterizing Parallel Program Performance

 \blacksquare processor cores, T_k is the running time using k cores

- Def. Speedup: $S_p = T_1 / T_p$
 - S_p is relative speedup if T_1 is running time of parallel version of the code running on 1 core.
 - S_p is absolute speedup if T_1 is running time of sequential version of code running on 1 core.
 - Absolute speedup is a much truer measure of the benefits of parallelism.
- Def. Efficiency: $E_p = S_p / p = T_1 / (pT_p)$
 - Reported as a percentage in the range (0, 100].
 - Measures the overhead due to parallelization

Performance of psum-local

Threads (t)	1	2	4	8	16
Cores (p)	1	2	4	4	4
Running time (T_p)	1.06	0.54	0.28	0.39	0.30
Speedup (S_p)	1	1.9	3.8	3.7	3.5
Efficiency (E_p)	100%	98%	95%	91%	88%

- Efficiencies > 90% are very good
- But only because our example is easily parallelizable
- Real codes are often much harder to parallelize
 - e.g., parallel quicksort later in this lecture

Amdahl's Law

- Captures the difficulty of using parallelism to speed things up.
- Overall problem
 - T Total sequential time required
 - p Fraction of total that can be sped up $(0 \le p \le 1)$
 - k Speedup factor

Resulting Performance

- $T_k = pT/k + (1-p)T$
 - Portion which can be sped up runs k times faster
 - Portion which cannot be sped up stays the same
- Least possible running time:
 - k = ∞
 - $T_{\infty} = (1-p)T$

Amdahl's Law Example

Overall problem

- T = 10 Total time required
- p = 0.9 Fraction of total which can be sped up
- k = 9 Speedup factor

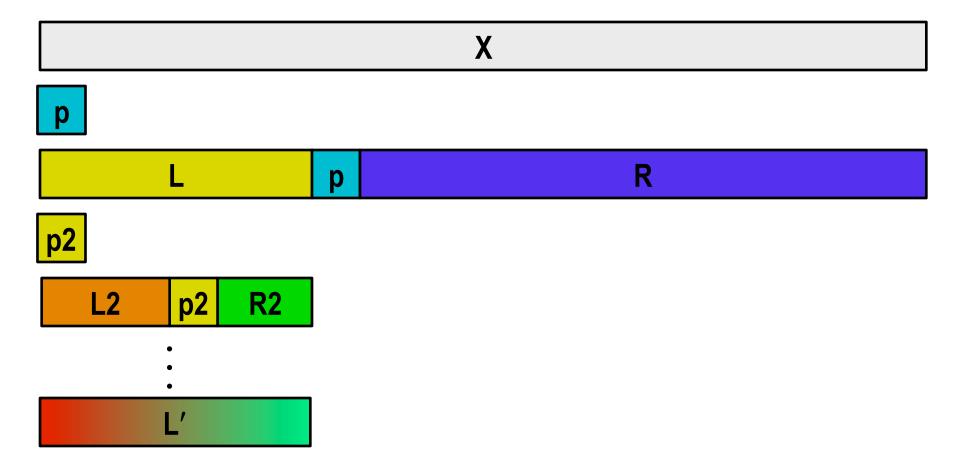
Resulting Performance

- $T_9 = 0.9 * 10/9 + 0.1 * 10 = 1.0 + 1.0 = 2.0$
- Least possible running time:
 - $T_{\infty} = 0.1 * 10.0 = 1.0$

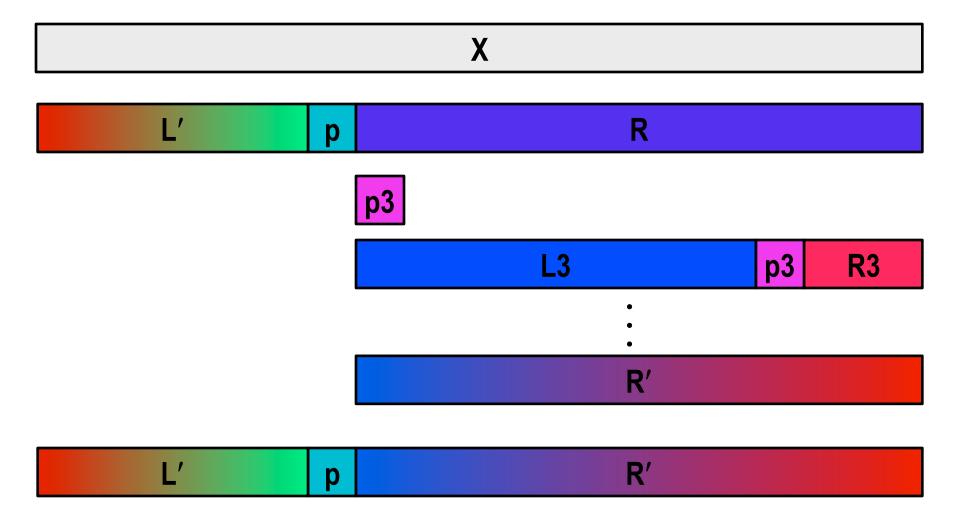
A More Substantial Example: Sort

- Sort set of N random numbers
- Multiple possible algorithms
 - Use parallel version of quicksort
- Sequential quicksort of set of values X
 - Choose "pivot" p from X
 - Rearrange X into
 - L: Values ≤ p
 - R: Values ≥ p
 - Recursively sort L to get L'
 - Recursively sort R to get R'
 - Return L' : p : R'

Sequential Quicksort Visualized



Sequential Quicksort Visualized



Sequential Quicksort Code

```
void qsort serial(data t *base, size t nele) {
  if (nele \le 1)
    return;
  if (nele == 2) {
    if (base[0] > base[1])
      swap (base, base+1);
    return;
  }
  /* Partition returns index of pivot */
  size t m = partition(base, nele);
  if (m > 1)
   qsort serial(base, m);
  if (nele-1 > m+1)
    qsort serial(base+m+1, nele-m-1);
```

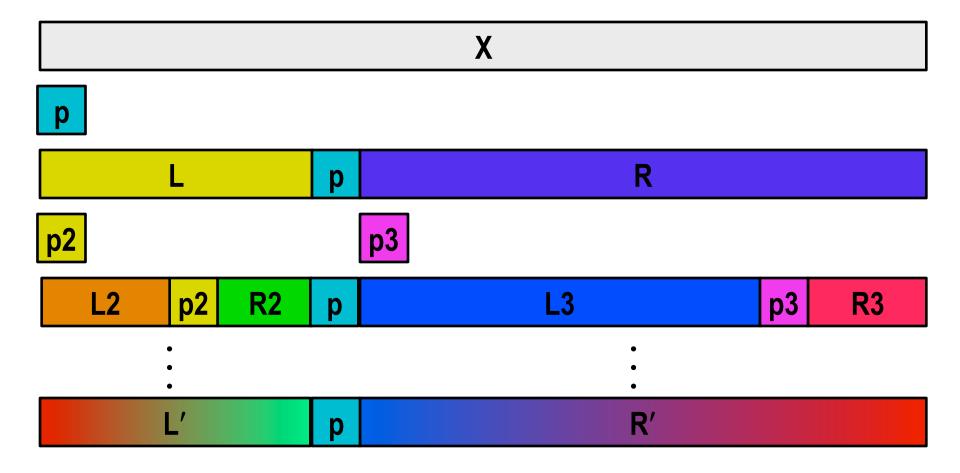
Sort nele elements starting at base

Recursively sort L or R if has more than one element

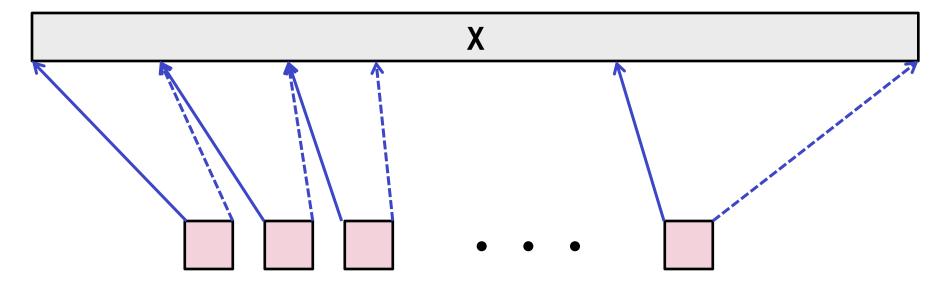
Parallel Quicksort

- Parallel quicksort of set of values X
 - If N ≤ Nthresh, do sequential quicksort
 - Else
 - Choose "pivot" p from X
 - Rearrange X into
 - L: Values ≤ p
 - R: Values ≥ p
 - Recursively spawn separate threads
 - Sort L to get L'
 - Sort R to get R'
 - Return L' : p : R'

Parallel Quicksort Visualized



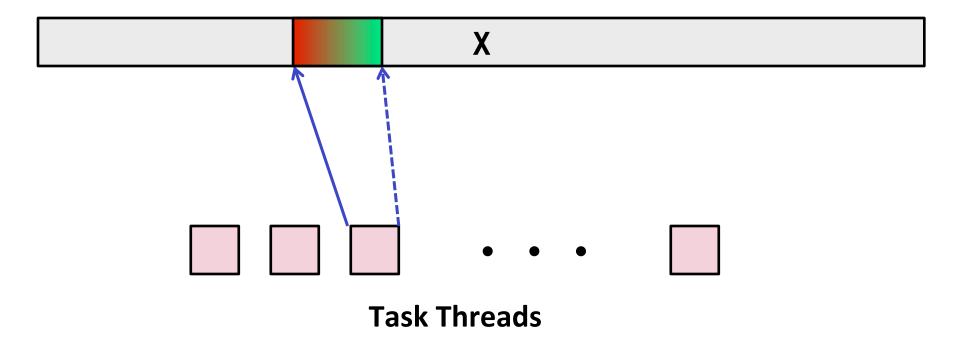
Thread Structure: Sorting Tasks



Task Threads

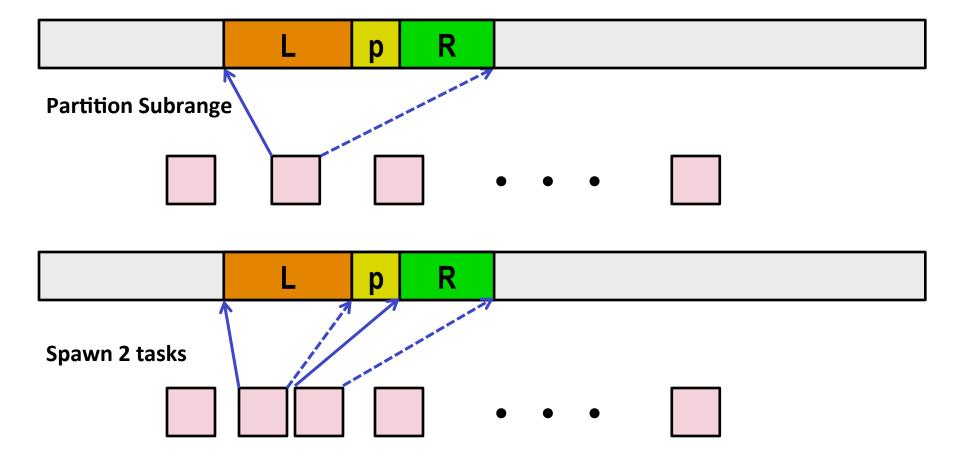
- Task: Sort subrange of data
 - Specify as:
 - base: Starting address
 - nele: Number of elements in subrange
- Run as separate thread

Small Sort Task Operation



Sort subrange using serial quicksort

Large Sort Task Operation



Top-Level Function (Simplified)

```
void tqsort(data_t *base, size_t nele) {
    init_task(nele);
    global_base = base;
    global_end = global_base + nele - 1;
    task_queue_ptr tq = new_task_queue();
    tqsort_helper(base, nele, tq);
    join_tasks(tq);
    free_task_queue(tq);
}
```

- Sets up data structures
- Calls recursive sort routine
- Keeps joining threads until none left
- Frees data structures

Recursive sort routine (Simplified)

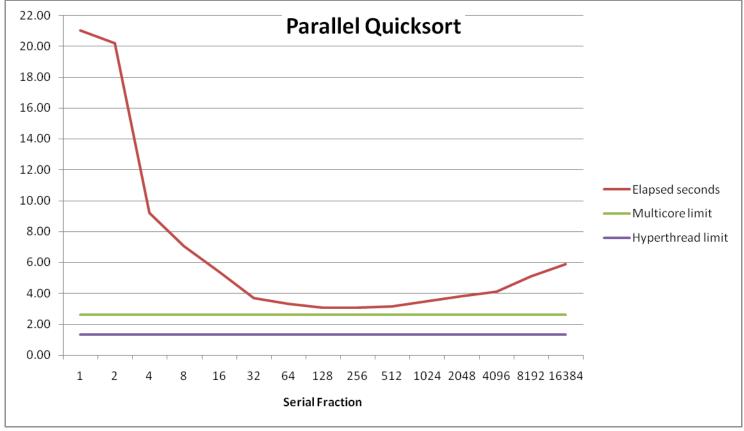
- Small partition: Sort serially
- Large partition: Spawn new sort task

Sort task thread (Simplified)

```
/* Thread routine for many-threaded quicksort */
static void *sort thread(void *vargp) {
    sort task t *t = (sort task t *) varqp;
    data t *base = t->base;
    size t nele = t->nele;
    task queue ptr tq = t->tq;
    free (vargp);
    size t m = partition(base, nele);
    if (m > 1)
        tqsort helper(base, m, tq);
    if (nele-1 > m+1)
        tqsort helper(base+m+1, nele-m-1, tq);
    return NULL;
```

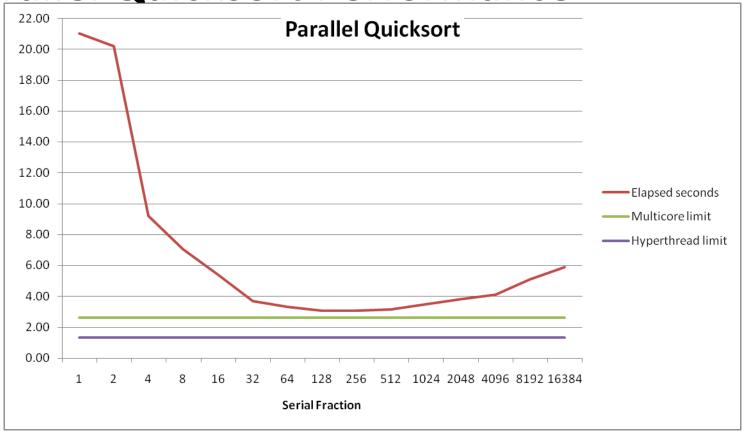
- Get task parameters
- Perform partitioning step
- Call recursive sort routine on each partition

Parallel Quicksort Performance



- Serial fraction: Fraction of input at which do serial sort
- Sort 2³⁷ (134,217,728) random values
- Best speedup = 6.84X

Parallel Quicksort Performance



Good performance over wide range of fraction values

- F too small: Not enough parallelism
- F too large: Thread overhead + run out of thread memory

Amdahl's Law & Parallel Quicksort

Sequential bottleneck

- Top-level partition: No speedup
- Second level: ≤ 2X speedup
- k^{th} level: $\leq 2^{k-1}X$ speedup

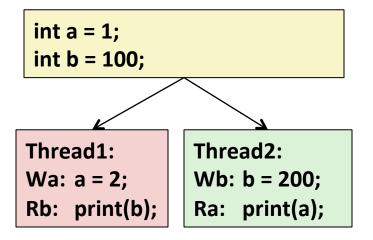
Implications

- Good performance for small-scale parallelism
- Would need to parallelize partitioning step to get large-scale parallelism
 - Parallel Sorting by Regular Sampling
 - H. Shi & J. Schaeffer, J. Parallel & Distributed Computing, 1992

Lessons Learned

- Must have parallelization strategy
 - Partition into K independent parts
 - Divide-and-conquer
- Inner loops must be synchronization free
 - Synchronization operations very expensive
- Beware of Amdahl's Law
 - Serial code can become bottleneck
- You can do it!
 - Achieving modest levels of parallelism is not difficult
 - Set up experimental framework and test multiple strategies

Memory Consistency



Thread consistency constraints
Wa——→ Rb

Wb----

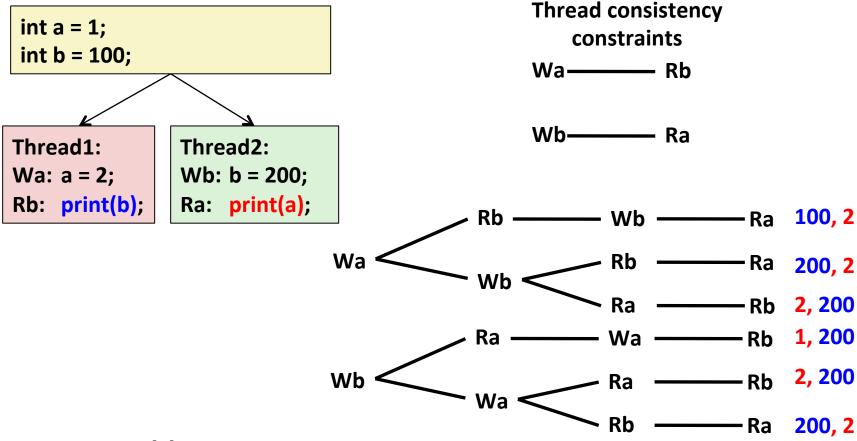
What are the possible values printed?

- Depends on memory consistency model
- Abstract model of how hardware handles concurrent accesses

Sequential consistency

- Overall effect consistent with each individual thread
- Otherwise, arbitrary interleaving

Sequential Consistency Example

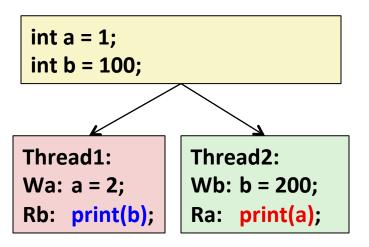


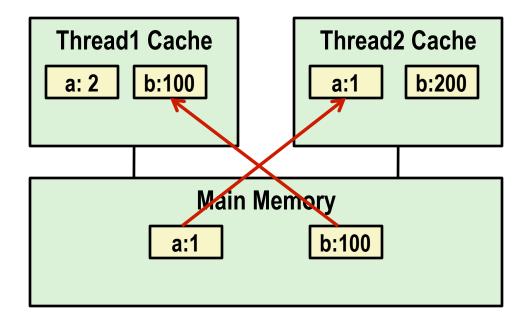
Impossible outputs

- 100, 1 and 1, 100
- Would require reaching both Ra and Rb before Wa and Wb

Non-Coherent Cache Scenario

Write-back caches, without coordination between them





print 1

print 100

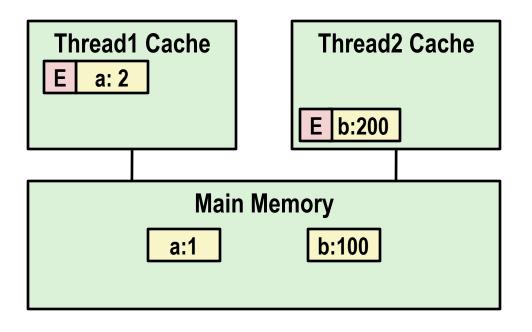
Snoopy Caches

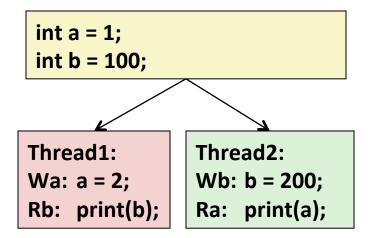
Tag each cache block with state

Invalid Cannot use value

Shared Readable copy

Exclusive Writeable copy





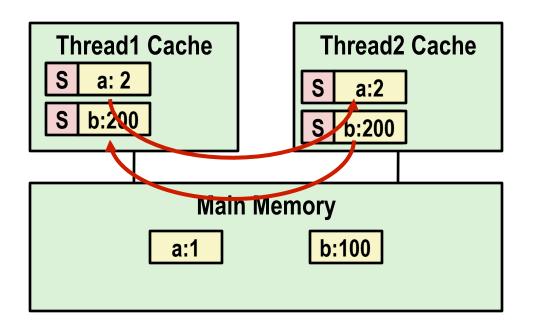
Snoopy Caches

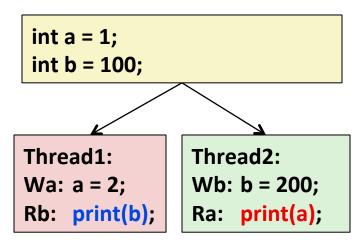
Tag each cache block with state

Invalid Cannot use value

Shared Readable copy

Exclusive Writeable copy



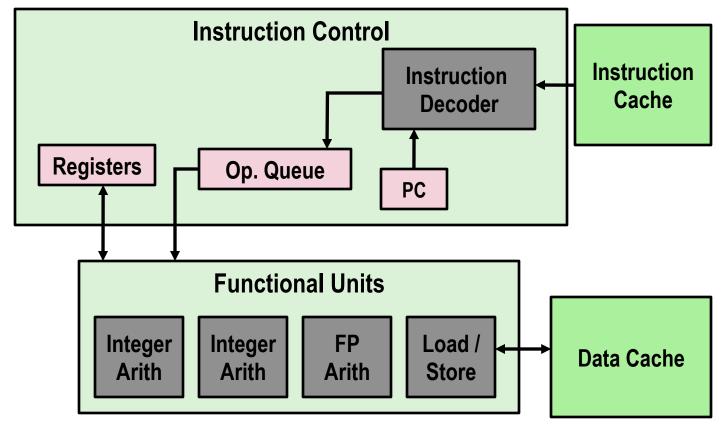


print 2

print 200

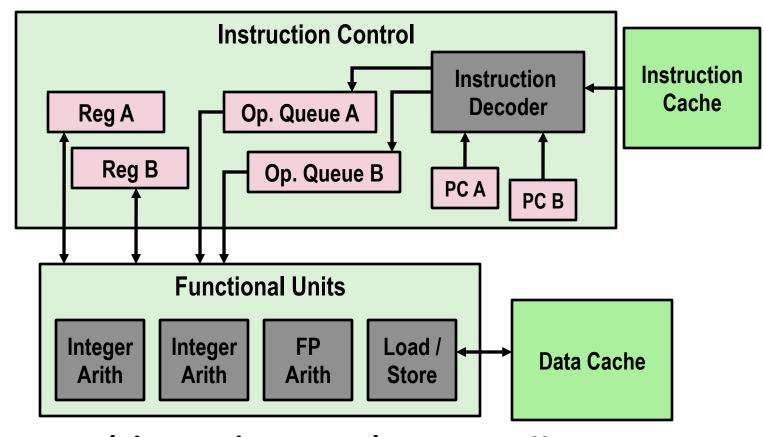
- When cache sees request for one of its E-tagged blocks
 - Supply value from cache
 - Set tag to S

Hyperthreading: Out-of-Order Processor Structure



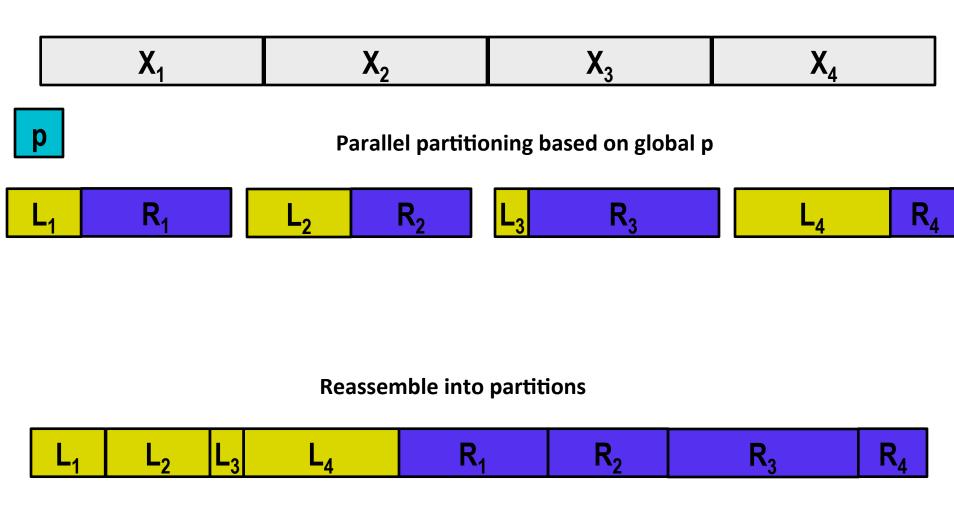
- Instruction control dynamically converts program into stream of operations
- Operations mapped onto functional units to execute in parallel

Hyperthreading Implementation



- Replicate enough instruction control to process K instruction streams
- K copies of all registers
- Share functional units

Parallelizing Partitioning Step



Experience with Parallel Partitioning

- Could not obtain speedup
- Speculate: Too much data copying
 - Could not do everything within source array
 - Set up temporary space for reassembling partition